

# TAO SUN

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## SUMMARY

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Tao Sun is currently pursuing a Ph.D. degree with NEUTRON Laboratory at Nanjing University of Aeronautics and Astronautics, supervised by Prof. Poramate Manoonpong and Zhendong Dai. His primary research aim is to investigate adaptive neural control based on central pattern generators, reflex chains, sensory feedback and learning mechanisms. The control can not only enable legged robots (e.g., quadruped robots) to autonomously generate adaptive self-organized locomotion and also contribute to the understanding of biological neural mechanisms of animals. A secondary objective is to develop a generic adaptive neural controller, which can directly be applied in various legged robots with different morphology. The research aims have almost been accomplished. His dissertation is titled adaptive neural control for self-organized locomotion of legged robots, and he will graduate with a PhD degree before April 2021.



## EDUCATION

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### Nanjing University of Aeronautics and Astronautics

*PhD of Machine design and theory*

Nanjing, China

Apr. 2016 – Present

### Nanjing University of Aeronautics and Astronautics

*Master of Machine design and theory*

Nanjing, China

Sep. 2014 – Sep. 2016

### Anhui Polytechnic University

*Bachelor of Process Equipment and Control Engineering*

Wuhu, China

Sep. 2010 – May 2014

## EXPERIENCE

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### PhD student

*College of Mechanical and Electrical Engineering, Nanjing University of Aeronautics and Astronautics*

Oct. 2020 – Present

*Nanjing, China*

- Preparing my thesis for applying a PhD degree

### Visiting researcher

*SDU Biorobotics, University of Southern Denmark*

Oct. 2019 – Sep. 2020

*Odense, Denmark*

- Developed a distributed force feedback-based reflex with online learning for adaptive quadruped robot control
- Performed a comparative study of adaptive interlimb coordination mechanisms for self-organized robot locomotion (comparing between continuous phase modulation and phase resetting of decoupled CPGs)

### PhD student

*College of Mechanical and Electrical Engineering, Nanjing University of Aeronautics and Astronautics*

Jan. 2018 – Sep. 2019

*Nanjing, China*

- Investigated neural control with adaptive physical and neural communications for reusable quadruped locomotion
- Investigated adaptive neural control for self-organized locomotion and obstacle negotiation of quadruped robots
- Developed a small-sized reconfigurable quadruped robot with multiple sensory feedback

### Robotic engineer

*College of Mechanical and Electrical Engineering, Nanjing University of Aeronautics and Astronautics*

Apr. 2016 – Dec. 2017

*Nanjing, China*

- Developed control algorithms for high slope walking of a hydraulic quadruped robot
- Developed a hardware system of a hydraulic quadruped robot

### Master student

*College of Astronautics, Nanjing University of Aeronautics and Astronautics*

Jun. 2014 – Sep. 2016

*Nanjing, China*

- Investigated path planning with lidar of mobile robots
- Investigated gait planning and foot trajectory optimization for efficient locomotion of hydraulic quadruped robots

## PRESENTATION

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### Oral

- International Youth Conference of Bionic Engineering (IYCBE 2018), "Adaptive neural control for self-organized locomotion and obstacle negotiation of quadruped robots", 7th-9th November 2018, Odense, Denmark.
- China Denmark Bio-inspired Engineering Seminar, "Adaptive neural control with adaptive physical and neural communications for quadruped locomotion", 15th October 2018, Nanjing, China.

### Post

- The 2nd National Robot Innovation and Design Competition, "A small-sized quadruped robot for studying bio-inspired locomotion control", 23rd – 26th September 2020, Xi'an, China.
- The 27th IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN 2018), "Adaptive neural control for self-organized locomotion and obstacle negotiation of quadruped robots", Aug. 2018, Nanjing, China.

## AWARD

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- The third prize in the 2nd in Robot Innovation and Design Competition of China Graduate Students, 23rd – 26th September 2020, Xi'an, China.
- The third prize of "Jerry Cup" in Energy Equipment Innovation Design Competition of China Graduate Students, 2020, China.
- Scholarship for supporting visiting research one year in Denmark from China Scholarship Council, 2019, China
- The third prize in the 7th "Tiangong Cup" of postgraduate innovative experiment competition, 30th November 2018, China.

## PUBLICATIONS

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1. Sun, T., Shao, D., Dai, Z., & Manoonpong, P. (2018, August). Adaptive neural control for self-organized locomotion and obstacle negotiation of quadruped robots. In 2018 27th IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN) (pp. 1081-1086). IEEE.
2. Sun, T., Xiong, X., Dai, Z., & Manoonpong, P. (2020). Small-Sized Reconfigurable Quadruped Robot With Multiple Sensory Feedback for Studying Adaptive and Versatile Behaviors. *Frontiers in Neurorobotics*, 14, 14.
3. Sun, T., Dai, Z., & Manoonpong, P. (2020.1). Robust and reusable self-organized locomotion of legged robots under adaptive physical and neural communications. *IEEE Transactions on Cybernetics* (revision).
4. Sun, T., Dai, Z., & Manoonpong, P. (2020.8). Distributed force feedback-based reflex with online learning for adaptive quadruped motor control. *Neural Networks* (under review).
5. Sun, T., Xiong, X., Dai, Z., Dai O., & Manoonpong, P. (2020). A comparative study of adaptive interlimb coordination mechanisms for self-organized robot locomotion. *Frontiers in Neurorobotics*, (revision)
6. Mario Calandra, Luca Patane, Tao Sun, Paolo Arena, Manoonpong P. (2020). Echo State Networks for estimating exteroceptive conditions from proprioceptive states in quadruped robots. *Frontiers in Neurorobotics* (under review)

## TEACHING

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1. Teaching "Phase adaptation under physical and neural communication for stable self-organized locomotion" in Embodied AI and Robotics Course, University of Southern Denmark, Nov. 7th 2019.
2. Teaching "Decoupled CPGs-based control for self-organized locomotion of legged robot" in Adaptive Locomotion Control Course, Nanjing University of Aeronautics and Astronautics, Dec. 5th 2020.

## TECHNICAL SKILLS

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**Languages:** Matlab, Python, C/C++, Lua, Latex

**Platforms:** Ubuntu, ADAMAS, ROS, CoppeliaSim, LpzRobots, Webots

**Developer Tools:** Git, Eclipse, Vim, UG NX, Inkscape, Kdenlive